



ACCESING HARDWARE BLISS

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BLISS – Short Presentation

BLISS stands for BeamLine Instrumentation Support Software.

BLISS is a control system which provides a global approach to run synchrotron experiments requiring to synchronously control motors, detectors and various acquisition devices thanks to hardware integration, Python sequences and an advanced scanning engine.

As a Python package, BLISS can be easily embedded into any Python application. BLISS data management features enable custom scripts to perform online data analysis.

BLISS ships with tools to enhance scientist users experience:

- a web portal to get access to BLISS applications
- a centralized logs viewer
- a configuration application
- a powerful command line interface
- an online data visualization application

Repository:

<https://gitlab.esrf.fr/bliss/bliss>

Documentation:

<https://bliss.gitlab-pages.esrf.fr/bliss/master/>



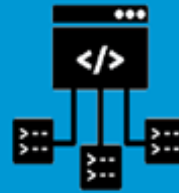
BLISS – Technical Choices and Design Principles

Written in Python 



All-in-one solution

configuration management, logging, communication protocols, hw drivers, shell (CLI), scanning engine, live data display, publishing and saving



Mini frameworks

motion control, regulation, monochromator, spectrometer, MCA...



I/O based on **gevent**
cooperative multi-tasking,
asyncio interoperability



Built-in direct hardware control

TANGO extensions for interoperability with other systems, or in case of shared hw



Scanning with the acquisition chain

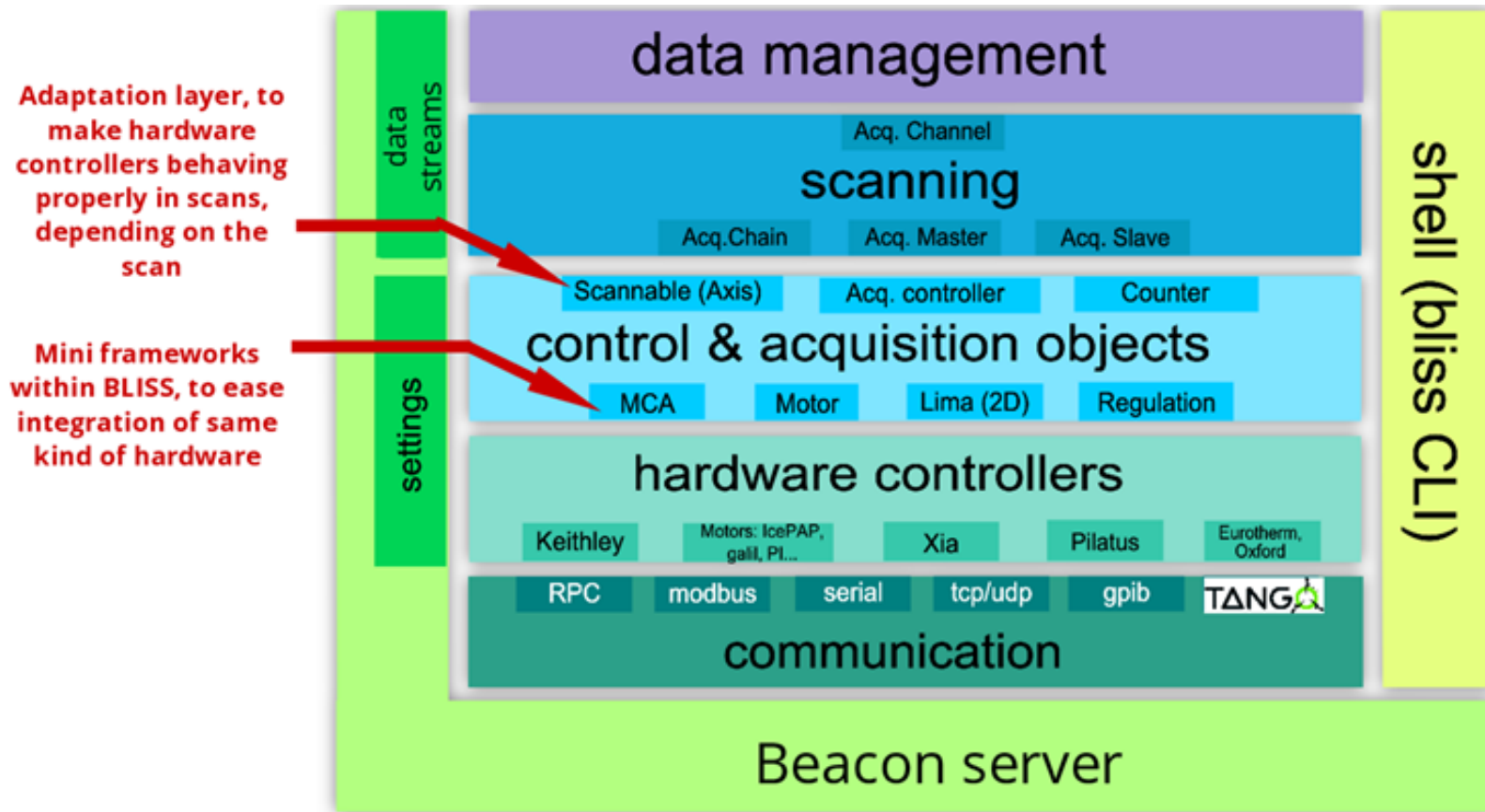
Tree structure to represent "trigger" relationship of devices in a scan



Data publishing,
acquisition made independent of storage



BLISS – Architecture Overview





BLISS – Beacon Server

Devices & sequences
configuration in YAML format

```

class: elmo
udp:
  url: 160.103.51.174
axes:
- name: nth
  acceleration: 36
  steps_per_unit: 30577
  velocity: 180.0
  home_velocity: 15
  velocity_low_limit: .inf
  velocity_high_limit: 360.0
  low_limit: -.inf
  high_limit: .inf
  sign: 1
  backlash: 0.0
- class: aerotech
  tcp:
    url: id31aerotech-1
  axes:
  - name: nth_aero
    acceleration: 5
    steps_per_unit: 1

```

configuration management
&
services



User sessions to group beamline devices for an experiment + Python setup file



Centralized logging and log viewer web application



database implementation



Settings cache
redis



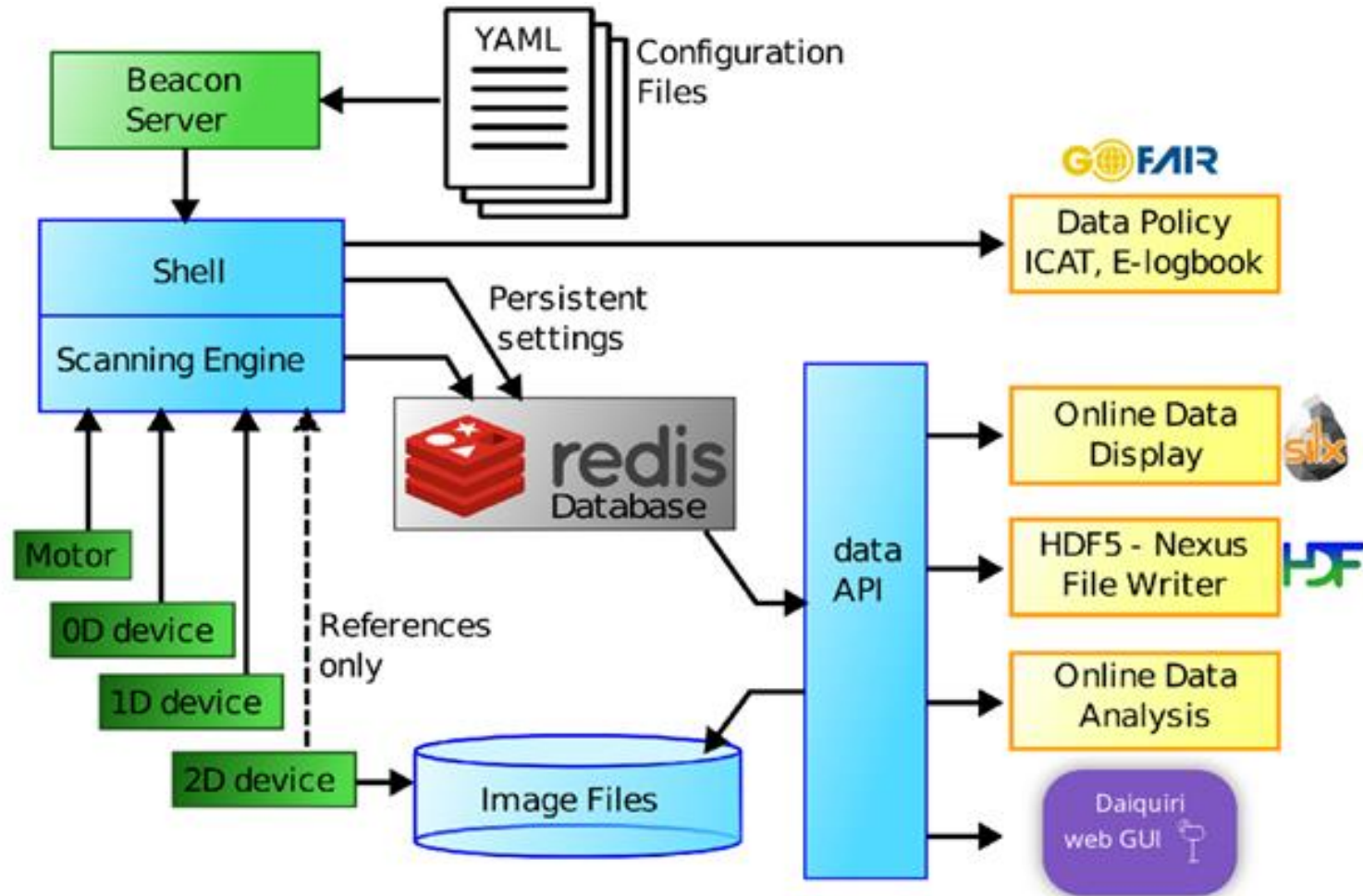
Web interface for configuration editing



Transient data store
redis



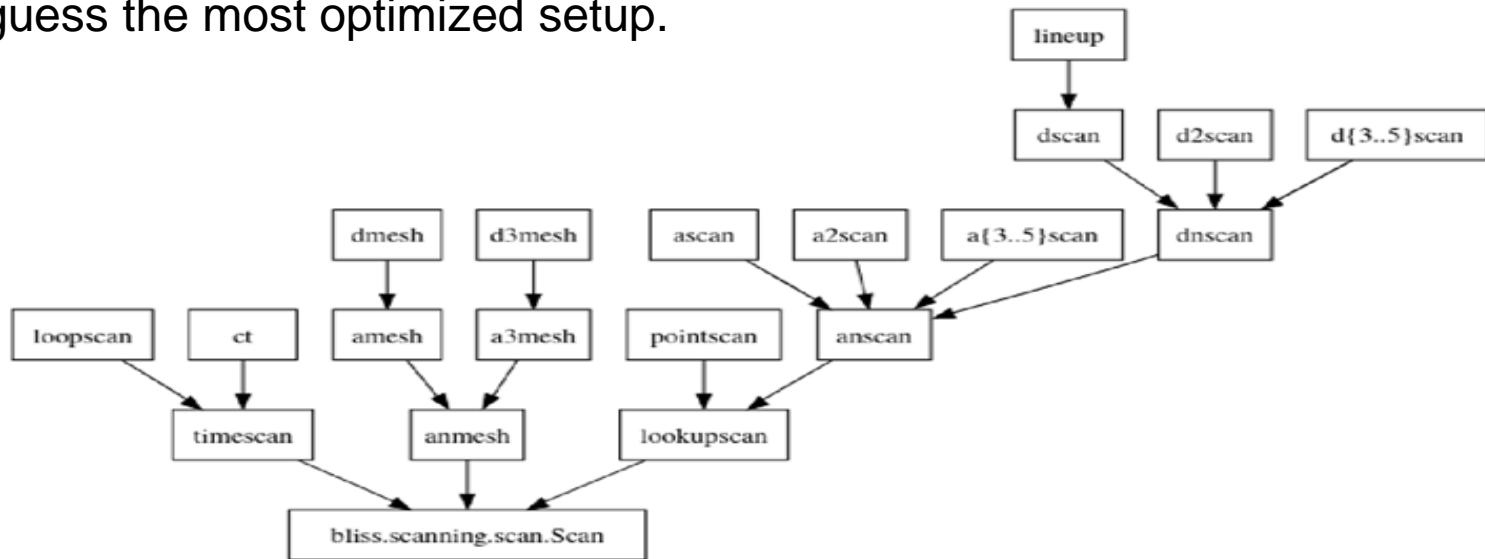
BLISS – Data Flow





BLISS – Scanning

- Powerful scanning engine for step-by-step and continuous scans.
- All scans are based on the same Scan object.
- The Scan object iterates through the Acquisition Chain that describes the triggering sequence (software or hardware).
- Data is sent to Redis and can be used for online display, online data analysis and saved.
- For “standard” scans the Acquisition Chain is built automatically, trying to guess the most optimized setup.





BLISS – What Users Like

- Python – scientist can take an advantage of a huge ecosystem for their own scripts
- Interactive data display tool – Flint
- Easy to switch between real and pseudo axes.
- Pseudo counters – any experimental parameter that can be measured during a scan.
- Software regulation loop – BLISS provides a Software Loop object that knows how to regulate with PID parameters.
- Data accessible immediately via Redis for custom online display and data analysis.
- Large number of hardware controllers, ready for immediate use.
- Easy to change and save setup – useful when changing sample environment.





BLISS – mxcubecore Implementation

- BLISS is written in python, which makes it very convenient to embed, rather than defining commands and channels, which might end up with a huge number.
- Install BLISS in the same conda environment as mxcubecore. We can thus import the configuration and the "session", which contains all the objects and scripts we need.
- The Bliss class implements how a session is initialised and gives access to any of the session objects. The initialisation is done at the start of the mxcubeweb server, with the first hardware object which uses bliss.
- A BLISS session represents an experimental setup associated with experiment control sequences. A session has a list of objects from configuration and a setup file. The BLISS session is an object, so it has an yaml configuration file, which lists the bliss objects that the session will provide. The session setup file is python file where scripts like `quick_realign`, `find_max_attenuation`, `centrebeam...` are instantiated. These scripts can then be run as beamline actions or used in Hardware objects like XRF and EnergyScan.
- To update state and value and thus emit the standard `valueChanged` and `stateChanged` signals, the HardwareObject `connect` method to connect an object from a bliss session is used.



BLISS – mxcube core Implementation

Bliss class	xml file
<pre>from mxcube.BaseHardwareObjects import HardwareObject from bliss.config import static class Bliss(HardwareObject): """Bliss class""" def __init__(self, *args): super().__init__(*args) def init(self, *args): """Initialis the bliss session""" cfg = static.get_config() session = cfg.get(self.get_property("session")) session.setup(self.__dict__, verbose=True)</pre>	<pre><object class="Bliss"> <session>mxcubebliss</session> </object></pre>
BlissNState class	Xml file
<pre>class BlissNState(AbstractNState): """Implementation of AbstarnState""" ... def init(self): self._bliss_obj = getattr(self.get_object_by_role("controller") self.actuator_name) self.connect(self._bliss_obj, "state", self.update_value)</pre>	<pre><object class="BlissNState"> <username>Detector Cover</username> <actuator_name>detcover</actuator_name> <object href="/bliss" role="controller"/> <values>{"IN": "IN", "OUT": "OUT"}</values> </object></pre>