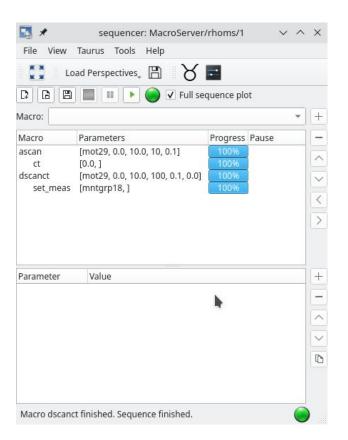
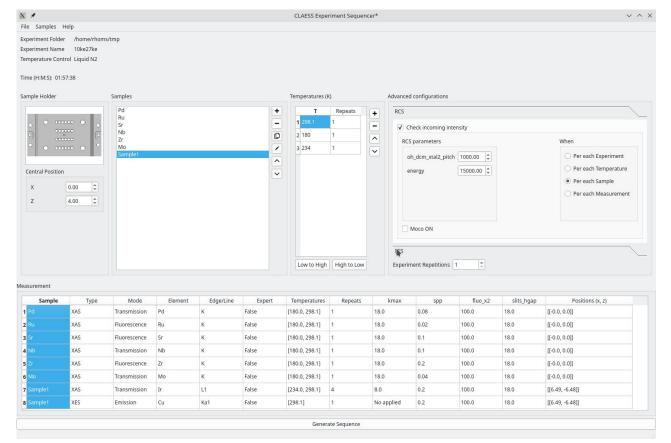
# Complex experiment applications at ALBA

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## Sardana sequencer



- Easy to use hooks
- Easy to Start/Pause/Restart/Stop
- Easy to save
- Easy to check progress status
- Load from text file (.txt), does not work hooks and params repeats, XML file support them but more complex to write.
- Do not possible to do loops, macro repeat is not adapted (feature/bug)
- Do not possible to do logic blocks (if/else)
- Do not possible to validate parameters (motor limits, valid integration time, ...)
- Do not possible to catch exceptions and recover from fails



#### *Initial requirements:*

Easy for external user Robust

Protections

Recover from fails

Repetitions

Automatic configuration

Temperature Control

Time estimation

Log files

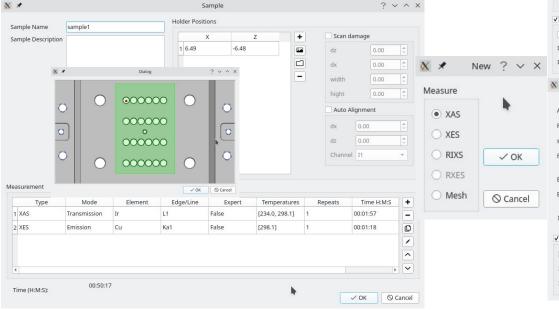
Simulation mode

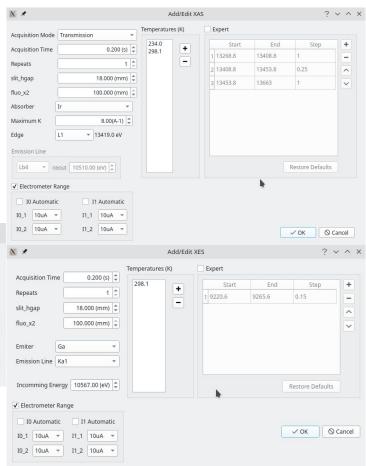
Work for 90% of proposals

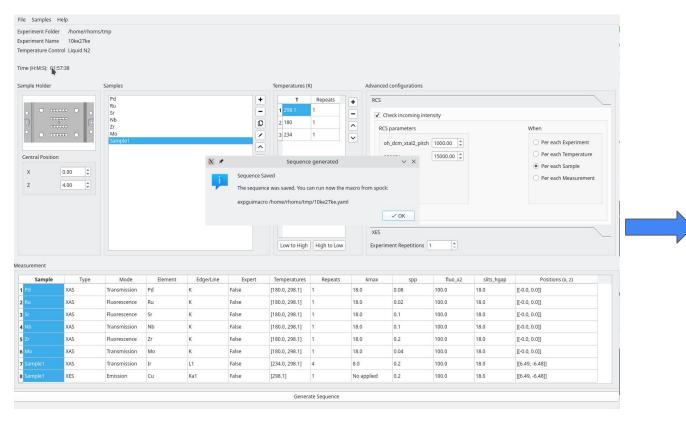
Sardana python 2.7

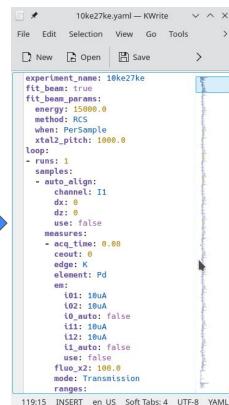
GUI python 3.9 pyqt=5.15

Sample position protection (green part)
Measure type selection
Automatic specific configuration, allow Expert mode
Electrometer automatic configuration

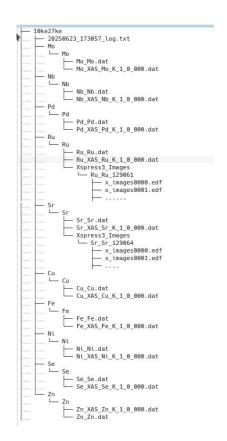








```
def run(self, filename, run, wait_fe, force_qExafs):
   self.demo = not run
   self._exp_data = None
   self. force gExfas = force gExafs
   self.log_file = None
       if self.demo:
            self.execMacro = self.info
       self._exp_data = None
       self.execMacro('blreconfig')
       if wait_fe:
            self.execMacro('blshopen')
       self._run(filename, wait_fe)
   except InterruptException:
   except Exception as e:
       if self._exp_data is not None:
            self._save_env()
            self.error('Macro aborted. Run blreconfig!')
            self.execMacro('blreconfig')
       if self.log_file is not None:
            for handler in self.log_file.handlers:
               handler.flush()
               self.log file.removeHandler(handler)
               del handler
```



Sardana TODOs / DONE
Use environment for state saving
(use deepcopy)
Implement abort/stop propagation on
gscan

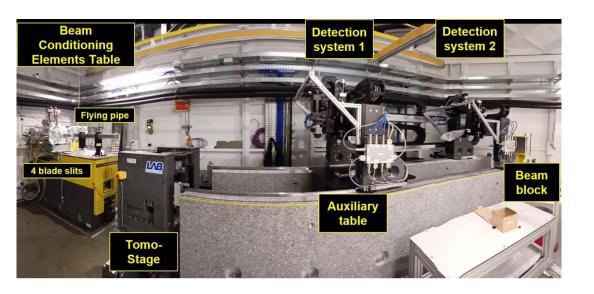
## BL22 CLAESS Experiment UI - what's next?

Connect GUI and MacroServer now both are running in the same python version:

- Allow to Start/Pause/Restart/Stop
- Show real progress
- Start from specific measure

Reuse it on BL16 Notos similar experiment measures.

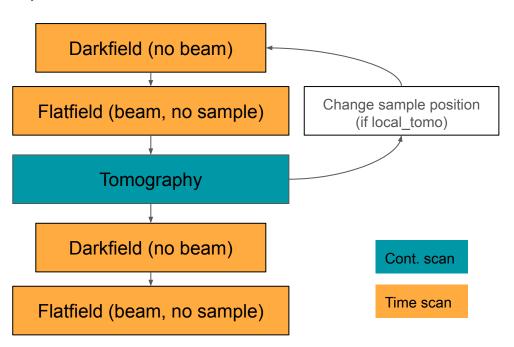
## **BL31 Faxtor**



Camera	FPS
PCO.edge 4.2	100
PCO DiMaX CS4	1102
C-Blue	85
Phantom S710	5700

GONIO: ACS

#### Sequence of scans:



#### Requirements:

- Handle fast shutter
- Asynchronous motor movements between scans
- Custom file storage
- Restart sequence from a given point
- Custom gonio behaviour:
  - Custom acceleration
  - Uninterrupted rotation

Scan configuration is serializable a Pydantic model

```
class TomoModel(BaseModel):
     tomo_steps: list[Step]
     current_slice_id: int =
class Step(BaseModel):
   sample_position: SamplePosition = SamplePosition()
   projections: int = Field(..., description="Number of images to take")
   exposure_time: Union[float, int] = Field(..., description="Time of the exposure")
   latency_time: Union[float, int] = Field(..., description="Time of the exposure")
   mode: Mode
   state: ScanState
   hooks: Dict = Field(default_factory=dict,exclude=True)
   point_id: int
   channel_refs:Dict[str, str] = Field(
       default_factory=dict,
       description="Key-value pairs for 2d channels and respective computed ref pattern"
   gonio_scan: bool = False
   gonio rotation: float = 180
```

- Scan configuration is serializable a Pydantic model
- Scan can be stored and loaded from environment

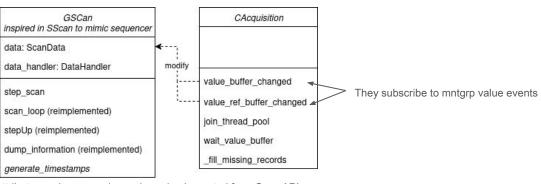
```
tomo_model = self.tomo_model.dict()
self.setEnv(bl31.ENV_KEYS.TOMO_MODEL, tomo_model)
```

```
model = TomoModel(**self.getEnv(bl31.ENV_KEYS.TOMO_MODEL))
```

- Scan configuration is serializable a Pydantic model
- Scan configuration can be stored and loaded from environment
- Scan configuration is updated at every step

```
def generator():
    for step in tomo_model:
        step.update(state=ScanState.Started)
        save tomo_model to env
        yield step
        step.update(state=ScanState.Finished)
        save tomo_model to env
```

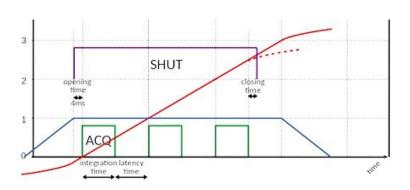
- Scan configuration is serializable a Pydantic model
- Scan configuration can be stored and loaded from environment
- Scan configuration is updated at every step
- Scan Framework API used:
  - Inherit from GScan and CAcquisition
  - We could reuse more code



Attributes and commands used or reimplemented from Scan API

## BL31 Faxtor Tomo Scan: shutter

- Time to open and time to close is considered in order to avoid sample damage
- Uses MultipleSynchDescription and Shutter object
- Shutter in measurement group
- According to step, its TriggerGate Axis gets configured
  - Darkfield: disabled
  - Flatfield: master of camera
  - Tomo: slave of gonio, master of camera



## **BL31 Faxtor Tomography UI**

