

Some "things" we want to know

Åke Andersson Accelerator Development Group

Outlook

Abstract:

We will try to list some properties of an accelerator, that is of high interest to know. We will then encounter some concepts commonly used in the control room discussions, and I will try to explain them. The presentation will be skewed towards ring accelerators like our storage rings.

MAX IV 3 GeV Storage Ring

Outlook

Some "things" we'd like to know about our storage ring:

- The beam position
- The beam focusing (quadrupole magnet strengths)
- The beam focusing corrections (sextupole magnet strengths)
- The longitudinal focusing of the beam (cavity voltages)
- The beam intensity ("The current")
- The beam energy
- The beam energy spread and the bunch lengths
- The beam size and angular spread in hor. and vert. dimension
- The dominant electron loss mechanisms (max deviation in position/angle or energy)

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MAX IV 3 GeV ring

- **Bending (or dipole) magnets • Quadrupole magnets** Sextupole magnets
- Octupole magnets

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MAX IV 3 GeV ring DC magnets

• Each cell is realized as one mechanical unit containing all magnet elements. •Each unit consists of a bottom and a top yoke half, machined out of one solid iron block, 2.3-3.4 m long.

- a U5 bottom half \rightarrow
- \downarrow an assembled U5

 $M₂$

 U_4

 $M1$

 111

 112

 $U₃$

Slide by Martin Johansson

The beam position

Don't require much accelerator theory \odot .

OFS Cu

ø 22/24 mm

Photo courtesy E. Al-dmou

• Most important for the SR users, are the positions around the beam line source point, i.e the Insertion Device (ID).

The beam position

- The beam should be positioned to within one tenth of the hor/vert beam size (54um/4um). The BPMs have this relative (short term) precision, but the absolute position must be repeatedly verified.
- In the surrounding octupoles we have auxiliary windings (Trim Coils) on all poles.
- We create a weak quadrupolar field by means of the trim coils. The beam can only pass unaffected through this field, if it passes in the so-called magnetic centre. The absolute "zero position" is this centre.
- Beam Based Calibration (BBC) , is the procedure by which we calibrate the nearby BPM to report $(x,z) = (0,0)$ for exactly this beam position.
- Sloppy expression: "Offsets measurements".
- It takes up to 16 hours to calibrate all 200 BPMs, verifying the zero position to better than a few microns. Refined and faster methods to come….

The beam focusing

• Here is needed some more theory:

A moving co-ordinate system

Imagine that we follow a reference particle around the storage ring. Let's calculate how **another** particle moves in x and z directions, when it is not perfectly on the reference orbit:

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Magnet strengths

The movement will be dependent on the magnet strengths, given by:

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Equations of motion

 $x' = dx/ds$

with $\delta = (p - p_0)/p_0$, being the relative momentum deviation

$$
x'' + (h^{2} + k)x = h\delta - (2hk + h^{3} + \frac{1}{2}m)x^{2} + h'xx' + \frac{1}{2}hx'^{2} + (k + 2h^{2})x\delta + \frac{1}{2}(h'' + hk + m)z^{2} + h'zz' - \frac{1}{2}hz'^{2} - h\delta^{2}
$$

and

 $z'' - kz = (2hk + m)xz + h'xz' + h'x'z + hx'z' + kx\delta$

Åke Andersson, SLRI Thailand, 15 August, 2016 Needs simplification!

Eq. of motion to first order, at p_0

$$
x''(s) + (h2(s) + k(s))x(s) = 0
$$

$$
z''(s) - k(s)z(s) = 0
$$

constraints for a storage ring

$$
h(s) = h(s + C_0) \qquad k(s) = k(s + C_0)
$$

Similar to:

Solution:

$$
x''(t) + \left(\frac{k}{m}\right)x(t) = 0 \qquad \qquad x(t) = A\sin(\omega t + \varphi), \omega = \sqrt{k/m}
$$

Hill differential equation

George William Hill

George William Hill

US astronomer, 1838-1914

$$
x''(s) + (h2(s) + k(s))x(s) = 0
$$

$$
z''(s) - k(s)z(s) = 0
$$

constraints for a storage ring

 $h(s) = h(s + C_0)$ $k(s) = k(s + C_0)$

Solution:

$$
x(s) = A \sqrt{\beta_x(s)} \sin(\Psi_x(s) + \Psi_0) , \quad \text{where } \Psi_x(s) = \Big|
$$

where
$$
\Psi_x(s) = \int_0^s \frac{d\hat{s}}{\beta(\hat{s})}
$$

Hill differential equation

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$$
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constraints for a storage ring

 $h(s) = h(s + C_0)$ $k(s) = k(s + C_0)$

Solution:

$$
especially Q_x = \frac{1}{2\pi} \int_0^{C_0} \frac{d\hat{s}}{\beta(\hat{s})}
$$

Hill differential equation

 $\beta(s)$ is also periodic, $\beta(s) = \beta(s + C_0)$, and fullfils:

$$
\frac{1}{2}\beta\beta'' - \frac{1}{4}\beta' + \beta^2(h^2 + k) = 1
$$

This is the "famous" beta-function, that we try to measure in the control room.

Particle envelop

One electron will turn after turn pass the same svalue with different Ψ , $\Psi(s) \neq \Psi(s + C_0)$. It will "track out" an envelop $E(s) = A\sqrt{\beta(s)}$

Courtesy K. Wille, The physics of particle accelerators

Horizontal beam envelop, or beam size

The horizontal rms beam size is given by:

These equilibria are reached within tens of milliseconds after a beam is injected, or after the stored beam was disturbed. It is a feature of electron (/positron) storage rings, where the quantum nature of photon emission rules.

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The horizontal rms beam size is given by:

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Dispersion function

The dispersion function η(s), is the periodic solution to the inhomogenous equ: $\eta''(s) + (h^2(s) + k(s))\eta(s) = h(s)$

 $\eta(s)$ δ Describes the closed orbit for a particle with a relative momentum deviation $\delta = (p - p_0)/p_0$

Important message

If we can verify/measure k(s), h(s), $\beta_{\sf x}$ (s), η(s) both the horizontal beam emittance and the beam energy spread are given through the so-called synchrotron radiation integrals.

The Integrals

We restrict our attention to guide fields made up of a number of magnetic segments - magnets or straight sections. The functions ρ and n are assumed to have constant values within a given magnet, but vary abruptly at the entrance and exit boundaries. The integrals of interest are given by:

$$
I_1 = \oint (\eta/\rho) ds = \sum_{i} \frac{\ell_i}{\rho_i} \langle \eta \rangle_i
$$
 (1)

$$
I_2 = \oint (1/\rho^2) ds = \sum_{i} \frac{I_i}{\rho_i^2}
$$
 (2)

$$
I_3 = \oint |1/\rho|^3 ds = \sum_{i} \frac{\ell_i}{|\rho_i|^3}
$$
 (3)

$$
I_4 = \oint \frac{(1 - 2n)\eta}{\rho^3} ds = \sum_{i} \left[\frac{\ell_i}{\rho_i^3} \zeta \eta \right]_i - 2t_i \left\langle \frac{n\eta}{\rho^3} \right\rangle_i \tag{4}
$$

$$
I_5 = \oint \frac{H}{|\rho|^3} ds = \sum_{i} \frac{l_i}{|\rho_i|^3} \langle H \rangle_i
$$
 (5)

We have used the notation $\langle f \rangle$ for the mean value of f in the ith segment whose length is f_i . The function H(s) is defined bv

$$
H = \frac{1}{\beta} \left[\eta^2 + (\beta \eta' - \frac{1}{2} \beta \eta)^2 \right] \tag{6}
$$

with $\beta' = d\beta/ds$, and $\eta' = d\eta/ds$. It should be noted right away that at least one factor of $1/\rho$ appears in each integral; so the straight sections or pure quadrupoles make no contribution.

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EVALUATION OF SYNCHROTRON RADIATION INTEGRALS*

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Outlook

Some "things" we'd like to know about our storage ring:

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- \bullet The beam focusing corrections (sextupole magnet strengths)
- The longitudinal focusing of the beam (cavity voltages)
- \bullet The beam intensity ("The durrent")
- The beam energy

Will be known at low current in the ring!

- The beam energy spread and the bunch lengths
- The beam size and angular spread in hor. and vert. dimension
- The dominant electron loss mechanisms (max deviation in position/angle or energy)

- We add a tiny dipole field by help of a "corrector" magnet
- Observe the new orbit in the ring, at 200 locations (BPMs).
- We do it with 200 different correctors horizontally.
- We do it with 190 different correctors vertically.
- Finally we change the beam energy up and down, by a known amount (typically with a few tenths of a %)
- Observe the two orbits, at 200 BPMs.
- The horizontal positions give the dispersion functions (at BPMs).
- The above procedure is called Orbit Response Matrix measurement, and takes about one hour.

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$$
x_c(s) = \frac{x'_k}{2\sin(\pi Q_x)} \sqrt{\beta_x(s_k)} \cos(\Psi_x(s) - \pi Q_x), \text{ where } \Psi_x(s) = \int_0^s \frac{d\hat{s}}{\beta(\hat{s})}
$$

Corrected Horizontal Beta-function Corrected Vertical Beta-function

Dispersion function, uncorrected

1.5 GeV Ring Linear Optics Design

1.5 GeV Ring Linear Optics Reality

$$
\frac{\text{Horizontal}}{\beta} < 5\%
$$
\nVertical $\frac{\Delta \beta}{\beta} < 12\%$

(spring 2017)

Magnets are as from supplier. No shunts are yet applied.

> Data by David K. **Olsson**

Verifying horizontal beam emittance

The horizontal rms beam size is given by:

$$
\sigma_x(s) = \sqrt{\varepsilon_x \beta(s) + \sigma_\varepsilon^2 \eta^2(s)}
$$

Equilibrium horizontal
beam emittance
energy spread

- At high current in the ring, we will have new equilibriums:
- However, we trust the measured beta and dispersion functions
- Measure at two locations the beam sizes, and

$$
\mathbb{E}_{x} = \frac{\sigma_{x,2}^{2} - \left(\frac{\eta_{x,2}}{\eta_{x,1}}\right)^{2} \sigma_{x,1}^{2}}{\beta_{x,2} - \left(\frac{\eta_{x,2}}{\eta_{x,1}}\right)^{2} \beta_{x,1}} \qquad \sigma_{\delta} = \left[\frac{\sigma_{x,2}^{2} - \left(\frac{\beta_{x,2}}{\beta_{x,1}}\right) \sigma_{x,1}^{2}}{\eta_{x,2}^{2} - \left(\frac{\beta_{x,2}}{\beta_{x,1}}\right) \eta_{x,1}^{2}}\right]^{1/2}
$$

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Sorry, hopefully I can sort out red areas in a second seminar. THANK YOU!!

